## Automated Completion of Statements and Proofs in Synthetic Geometry: an Approach based on Constraint Solving

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## Automated deduction in general



## Automated deduction in geometry



## Conjecturing and proving

- But real mathematical activity does not fit into this picture.
- Conjecturing/refuting/proving/producing lemmas, theories or definitions are interlaced activities. See Lakatos ${ }^{1}$
${ }^{1}$ Proofs and Refutations (1976).


## Our approach



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## Our approach



## Coherent Logic / Finitary Geometric Implications

- A formula of coherent logic (universally closed):

$$
A_{0}(\vec{x}) \wedge \ldots \wedge A_{n-1}(\vec{x}) \Rightarrow \exists \vec{y}\left(B_{0}(\vec{x}, \vec{y}) \vee \ldots \vee B_{m-1}(\vec{x}, \vec{y})\right)
$$

where universal closure is assumed, $A_{i}$ denotes an atomic formula, and $B_{j}$ denotes a conjunction of atomic formulae.

- No function symbols of arity $>0$ and no negations
- Many theories can be simply formulated in CL
- Every FOL theory can be translated into CL, possible with additional predicate symbols
- For instance, for each predicate symbol $R$, a new symbol $\bar{R}$ is introduced for $\neg R$, and the axioms: $\forall \vec{x}(R(\vec{x}) \wedge \bar{R}(\vec{x}) \Rightarrow \perp)$, $\forall \vec{x}(R(\vec{x}) \vee \bar{R}(\vec{x}))$


## Inference System for Coherent Logic

$$
\frac{\Gamma, a x, A_{0}(\vec{a}), \ldots, A_{n-1}(\vec{a}), \underline{B_{0}(\vec{a}, \vec{b}) \vee \ldots \vee B_{m-1}(\vec{a}, \vec{b})} \vdash P}{\Gamma, a x, A_{0}(\vec{a}), \ldots, A_{n-1}(\vec{a}) \vdash P} \mathrm{MP}
$$

where $a x$ is
$A_{0}(\vec{x}) \wedge \ldots \wedge A_{n-1}(\vec{x}) \Rightarrow \exists \vec{y}\left(B_{0}(\vec{x}, \vec{y}) \vee \ldots \vee B_{m-1}(\vec{x}, \vec{y})\right)$

$$
\frac{\Gamma, \underline{B_{0}(\vec{c})} \vdash P \quad \ldots \quad \Gamma, \underline{B_{m-1}(\vec{c})} \vdash P}{\Gamma, B_{0}(\vec{c}) \vee \ldots \vee B_{m-1}(\vec{c}) \vdash P} \text { QEDcs (case split) }
$$

$\overline{\Gamma, \underline{B_{i}(\vec{a}, \vec{b})} \vdash \exists \vec{y}\left(B_{0}(\vec{a}, \vec{y}) \vee \ldots \vee B_{m-1}(\vec{a}, \vec{y})\right)}$ QEDas (assumption)

$$
\overline{\Gamma, \perp \vdash P} \text { QEDefq (ex falso quodlibet) }
$$

## Inference System for Coherent Logic: Example

Consider the following two axioms:
ax1: $\forall x(p(x) \Rightarrow r(x) \vee q(x)) \quad a \times 2: ~ \forall x(q(x) \Rightarrow \perp)$
and the conjecture: $\forall x(p(x) \Rightarrow r(x))$

$$
\frac{\overline{a \times 1, a \times 2, p(a), r(a) \vdash r(a)} \text { QEDas } \frac{\overline{a \times 1, a \times 2, p(a), q(a), \perp \vdash r(a)}}{\frac{a \times 1, a \times 2, p(a), r(a) \vee q(a) \vdash r(a)}{a \times 1, a \times 2, p(a) \vdash r(a)}} \text { QEDefq }}{\text { MP(ax2) }} \text { MP(ax1) }
$$

The same proof in a forward manner, in a natural language form:
Consider an arbitrary a such that: $p(a)$. It should be proved that $r(a)$.

1. $r(a) \vee q(a)$ (by MP, from $p(a)$ using axiom ax1; instantiation: $X \mapsto a$ )
2. Case $r(a)$ :
3. Proved by assumption! (by QEDas)
4. Case $q(a)$ :
5. $\perp$ (by MP, from $q(a)$ using axiom ax2; instantiation: $X \mapsto a$ )
6. Contradiction! (by QEDefq)
7. Proved by case split! (by QEDcs, by $r(a), q(a)$ )

## Starting Ideas

- The pure forward chaining approach to ATP does not take the goal into account.
- SAT/SMT solvers have seen huge progress in the recent years.
- Encoding the problem of finding a Coherent Logic proof into SAT/SMT theories can give a form of multidirectional reasoning.


## Theorem Proving as Constraint Solving

- In traditional automated proving:
- the search is performed over a set of formulae, and it terminates once the goal formula or contradiction is found.
- a proof can then be reconstructed as a byproduct of this process.
- In our approach, proving as constraint solving:
- a proof of a given formula can be represented by a sequence of natural numbers, meeting some constraints;
- the search is performed globally over a set of possible proofs (i.e., over a set of possible sequences of natural numbers);
- a proof is found by a solver that finds a sequence that meets these conditions.
- a proper proof can be reconstructed from the found sequence.


## Encoded Proof: Example



## Related work

Surprisingly (as far as we know), this approach has hardly been studied extensively. Only, partly related:

- Todd Deshane, Wenjin Hu, Patty Jablonski, Hai Lin, Christopher Lynch, and Ralph Eric McGregor. Encoding First Order Proofs in SAT, CADE-21, 2007.
- Jeremy Bongio, Cyrus Katrak, Hai Lin, Christopher Lynch, and Ralph Eric McGregor. Encoding First Order Proofs in SMT. ENTCS, 198(2):71-84, 2008.


## Proof encoding and constraints

- We generate constraints that a sequence of natural numbers represents a valid proof.
- Proofs by cases are encoded by associating nesting information to each proof step.
- Each proof consists of steps of the following types: Assumption, MP, FirstCase, SecondCase, QEDbyCases, QEDbyAssumption, QEDbyEFQ
- Contents corresponds to a disjunction in a proof step, Goal is true iff Contents is the goal...
- There are also global constraints


## Example: Constraints for steps QEDbyEFQ

- Each proof step has one of the above sorts and meets some constraints
- For instance, if the step $s$ is of the kind QEDbyEFQ, then the following conditions hold:
(1) StepKind $(s)=$ QEDbyEFQ
(2) $s>0$
(3) contents $(s-1)(0)=\perp$
(4) step $s$ is the goal
(5) Nesting $(s)=\operatorname{Nesting}(s-1)$


## Pipeline

(1) A maximal proof length $M$ is given.
(2) Proof steps and the constraints are encoded by natural numbers.
(3) A constraint solver (for linear arithmetic, for instance), is invoked to find a model.
(9) There is a proof of length $\leq M$ iff there is a model for the constraints.
(5) If there is a model, then a proof can be reconstructed from it.
(0) A proof for a proof assistant, a readable proof, an illustrated proof then can be constructed from the proof.

## Completing incomplete premises: Abduction (1/5)

Given a theory $\mathcal{T}$ and a conjecture $G$, assuming that $\mathcal{T} \not \vDash G$ and $\mathcal{T} \not \models \neg G$, the objective is to find a set of atomic formulae $F$, such that it holds:

- $\mathcal{T}, F \vdash G$
- the set $\{\mathcal{T}, F\}$ is consistent

The formulas in $F$ are called the abducts.

## Completing incomplete premises: Abduction (2/5)

There can be additional conditions. In Larus (an abduct makes the step $i$ ):
(1) StepKind $(i)=$ Assumption
(2) Nesting $(i)=1$
(3) Cases $(i)=$ false
(4) ContentsPredicate $(i, 0)<\operatorname{sizeof}$ (Signature)
(5) for each argument $j$ (up to maximal arity):

ContentsArgument $(i, 0, j)<\operatorname{sizeof}($ Constants)
(6) Goal(i) $=$ false
(7) ContentsPredicate $(i, 0) \neq \perp$

## Completing incomplete premises: Abduction $(3 / 5)$

(1) $\mathrm{ax} 0: \forall X(p(X) \Rightarrow q(X))$
© $\mathrm{ax1}$ : $\forall X(q(X) \Rightarrow r(X) \vee s(X))$
© ax2: $\forall X(r(X) \Rightarrow \perp)$
Conjecture: $\forall X(s(X))$
The conjecture cannot be proved, but Larus offers two abducts:

1. set:
2. $((q(b)))$

Abducts CONSISTENT!
Conjecture: $\forall X(q(X) \Rightarrow s(X))$
2. set:

1. $((p(b)))$

Abducts CONSISTENT!
Conjecture: $\forall X(p(X) \Rightarrow s(X))$

## Completing incomplete premises: Abduction (4/5)



Let $A B C D$ be a quadrilateral. Let $E, F, G$ the midpoints of $A B, B C$ et $C D$ respectively. Let $H$ be a point.
Under which assumption the quadrilateral EFGH is a parallelogram ?
$\longrightarrow \mathrm{H}$ should be the midpoint of segment $A D$.

## Completing incomplete premises: Abduction $(5 / 5)$

Consider arbitrary $a, b, c, d, e, f, g, h$ such that:

- $\neg \operatorname{col}(b, d, a)$,
- $\neg \operatorname{col}(b, d, c)$,
- $\neg \operatorname{col}(a, c, b)$,
- $\neg \operatorname{col}(a, c, d)$,
- $\neg \operatorname{col}(e, f, g)$,
- $b \neq d$,
- $a \neq c$,
- midpoint $(a, e, b)$,
- midpoint $(b, f, c)$,
- midpoint $(c, g, d)$.

It should be proved that $p G(e, f, g, h)$.
Abducts found:

- midpoint $(d, h, a)$

1. $\operatorname{par}(a, c, e, f)$ (by MP, from $\neg c o l(a, c, b)$, midpoint $(b, f, c)$, midpoint $(a, e, b)$ using axiom triangle_mid_par_strict; instantiation: $A \mapsto a, B \mapsto c, C \mapsto b, P \mapsto f, Q$ $\mapsto e)$

## Completing incomplete goals: Deducts (1/2)



Let $A B C D$ be a quadrilateral. Let $E, F, G$, $H$ be the midpoints of the segments [AB], $[B C],[C D]$ and [DA] respectively.
What can we say about EFGH ?
$\longrightarrow$ EFGH is a parallelogram.

## Completing incomplete goals: Deducts (2/2)

It should be proved that $\quad(e, f, g, h)$.
2. $\operatorname{par}(a, c, e, f)$ (by MP, from $\neg \operatorname{col}(a, c, b)$, midpoint $(b, f, c)$, midpoint $(a, e, b)$ using axiom triangle_mid_par_strict; instantiation: $A \mapsto a, B \mapsto c, C \mapsto b, P \mapsto f, Q$ $\mapsto e)$
3. $\operatorname{par}(a, c, h, g)$ (by MP, from $\neg c o l(a, c, d)$, midpoint $(c, g, d)$, midpoint $(a, h, d)$ using axiom triangle_mid_par_strict; instantiation: $A \mapsto a, B \mapsto c, C \mapsto d, P \mapsto g, Q$ $\mapsto h)$
4. $\quad \operatorname{par}(e, f, g, h)$ (by MP, from $\operatorname{par}(a, c, e, f), \operatorname{par}(a, c, h, g), \neg \operatorname{col}(e, f, g)$ using axiom lemma_par_trans; instantiation: $A \mapsto e, B \mapsto f, C \mapsto a, D \mapsto c, E \mapsto g, F \mapsto$ h)
5. Proved by assumption! (by QEDas)

## Completing incomplete proofs: Hints (1/3)

9.3 Lemma. $\mathrm{B} a A c \wedge m \in A \wedge \mathrm{Mamc} \wedge r \in A \rightarrow \forall b[a \underset{\bar{r}}{\sim} b \rightarrow \mathrm{Bb} A c]$.
(Wenn a und $c$ auf entgegengesetzten Seiten der Geraden A liegen, und zwar spiegelbildlich bezüglich eines Punktes von $A$, und $r$ auf A liegt, so liegt jeder Punkt b der Halbgeraden $\mathrm{H}(\mathrm{ra})$ entgegengesetzt $z u$ c bezüglich $A$, Abb. 33.)


Abb. 33

Beweis: Sei $a \check{\tilde{r}} \quad b$. Nach Def. $6.1(i i)$ ist Brba $\vee$ Brab.

## Completing incomplete proofs: Hints (2/3)

- Hint can be found in an informal proof (for instance, in a textbook), from machine verifiable proof, or from memory!
- For a proof or a proof step, hint can specify:
- the predicate symbol
- arguments in the atomic formula
- the ordinal of a proof step
- the axiom applied in the step
- ...
- In other provers, such hints are extremely difficult to use
- In some cases, hints can lead to significant speed-ups


## Completing incomplete proofs: Hints $(3 / 3)$

- Using this approach, the user can add constraints either to help the prover or to find a specific proof.
- Examples:
- predicate $r$ must appear somewhere in the proof: fof (hintname0, hint, r(?,?), _, _)
- ax2 must be used in the proof at step 3 , instantiating both arguments with the same value fof(hintname 0 , hint, _, 3, ax2(A,A))
- Many generated abducts/deducts are ,,uninteresting " or mutually similar
- There are different restrictions in abduction considered in the literature and we will consider different criteria for filtering out ,,interesting" abducts/deducts (for instance, minimal in some sense)


## Conclusions

- We have shown that we can extend a prover, which uses constraint solving, so that it can complete:
- partially specified hypotheses
- partially specified conclusions
- partially specified proofs
- All three tasks fit naturally into proving as constraint solving paradigm: it is only that some constraints are added or deleted
- To our knowledge, this approach is new, and we are not aware of any other systems that tackle these three completion problems.

