Automated Completion of Statements and Proofs in Synthetic Geometry: an Approach based on Constraint Solving

Salwa Tabet Gonzalez Predrag Janičić Julien Narboux University of Belgrade, Serbia University of Strasbourg, France

Automated Deduction in Geometry, September 2023, Beograd.

▲口▶ ▲□▶ ▲ヨ▶ ▲ヨ▶ ヨー シスペ

#### Automated deduction in general



#### Automated deduction in geometry



◆□ > ◆母 > ◆臣 > ◆臣 > 善臣 - のへで

- But real mathematical activity does not fit into this picture.
- Conjecturing/refuting/proving/producing lemmas, theories or definitions are interlaced activities. See Lakatos <sup>1</sup>

<ロ> < 団> < 団> < 臣> < 臣> < 臣 > ○ < ? 26



▲口 > ▲母 > ▲目 > ▲目 > ▲目 > ▲日 >



▲口 > ▲母 > ▲目 > ▲目 > ▲目 > ▲日 >

#### Our approach



# Coherent Logic / Finitary Geometric Implications

• A formula of coherent logic (universally closed):

 $A_0(\vec{x}) \land \ldots \land A_{n-1}(\vec{x}) \Rightarrow \exists \vec{y} (B_0(\vec{x}, \vec{y}) \lor \ldots \lor B_{m-1}(\vec{x}, \vec{y}))$ 

where universal closure is assumed,  $A_i$  denotes an atomic formula, and  $B_j$  denotes a conjunction of atomic formulae.

- No function symbols of arity > 0 and no negations
- Many theories can be simply formulated in CL
- Every FOL theory can be translated into CL, possible with additional predicate symbols
- For instance, for each predicate symbol R, a new symbol R is introduced for ¬R, and the axioms: ∀x(R(x) ∧ R(x) ⇒ ⊥), ∀x(R(x) ∨ R(x))

#### Inference System for Coherent Logic

$$\frac{\Gamma, ax, A_0(\vec{a}), \dots, A_{n-1}(\vec{a}), \underline{B_0(\vec{a}, \vec{b})} \vee \dots \vee B_{m-1}(\vec{a}, \vec{b})}{\Gamma, ax, A_0(\vec{a}), \dots, A_{n-1}(\vec{a}) \vdash P}$$
MP

where 
$$ax$$
 is  
 $A_0(\vec{x}) \land \ldots \land A_{n-1}(\vec{x}) \Rightarrow \exists \vec{y} (B_0(\vec{x}, \vec{y}) \lor \ldots \lor B_{m-1}(\vec{x}, \vec{y}))$ 

$$\frac{\Gamma, \underline{B_0(\vec{c})} \vdash P \quad \dots \quad \Gamma, \underline{B_{m-1}(\vec{c})} \vdash P}{\Gamma, B_0(\vec{c}) \lor \dots \lor B_{m-1}(\vec{c}) \vdash P} \text{ QEDcs (case split)}$$

 $\frac{1}{\Gamma, \underline{B_i(\vec{a}, \vec{b})} \vdash \exists \vec{y} (B_0(\vec{a}, \vec{y}) \lor \ldots \lor B_{m-1}(\vec{a}, \vec{y}))} \text{ QEDas (assumption)}$ 

 $\overline{\Gamma, \bot \vdash P} \text{ QEDefq (ex falso quodlibet)}$ 

## Inference System for Coherent Logic: Example

and the conjecture:  $\forall x \ (p(x) \Rightarrow r(x))$ 



The same proof in a forward manner, in a natural language form:

Consider an arbitrary a such that: p(a). It should be proved that r(a).

- 1.  $r(a) \lor q(a)$  (by MP, from p(a) using axiom ax1; instantiation:  $X \mapsto a)$ 
  - 2. Case r(a):
    - 3. Proved by assumption! (by QEDas)
  - 4. Case q(a):
    - 5.  $\perp$  (by MP, from q(a) using axiom ax2; instantiation:  $X \mapsto a$ )
    - 6. Contradiction! (by QEDefq)
- 7. Proved by case split! (by QEDcs, by r(a), q(a))

- The pure forward chaining approach to ATP does not take the goal into account.
- SAT/SMT solvers have seen huge progress in the recent years.
- Encoding the problem of finding a Coherent Logic proof into SAT/SMT theories can give a form of multidirectional reasoning.

#### Theorem Proving as Constraint Solving

- In traditional automated proving:
  - the search is performed over a set of formulae, and it terminates once the goal formula or contradiction is found.
  - a proof can then be reconstructed as a byproduct of this process.
- In our approach, proving as constraint solving:
  - a proof of a given formula can be represented by a sequence of natural numbers, meeting some constraints;
  - the search is performed globally over a set of possible proofs (i.e., over a set of possible sequences of natural numbers);
  - a proof is found by a solver that finds a sequence that meets these conditions.
  - a proper proof can be reconstructed from the found sequence.

#### Encoded Proof: Example

0.	1 0 0	<pre>2 0 /* Nesting: 1; Step kind:0 = Assumption; Branching: no; p2(a) */</pre>
1.	1 13 1	4 0 6 0 /* Nesting: 1; Step kind:13 = MP-axiom:13; Branching: yes; p4(a) or p6(a) */
		0 /* From steps: (0) */
		0 /* Instantiation */
2.	2 2 0	4 0 /* Nesting: 2; Step kind:2 = First case;
		Branching: no; p4(a) */
з.	2 10	/* Nesting: 2; Step kind:10 =
		QED by assumption; */
4.	3 3 0	6 0 /* Nesting: 3; Step kind:3 = Second case;
		Branching: no; p6(a) */
5.	3 14 0	<pre>0 /* Nesting: 3; Step kind:14=MP-axiom:14);</pre>
		Branching: no; p0() */
		4 /* From steps: (4) */
		0 /* Instantiation */
6.	3 11	<pre>/* Nesting: 3; Step kind:11 = QED by EFQ;*/</pre>
7.	1 9	/* Nesting: 1; Step kind:9 = QED by cases;*/

◆□▶ ◆□▶ ◆三▶ ◆三▶ ○○○

Surprisingly (as far as we know), this approach has hardly been studied extensively. Only, partly related:

- Todd Deshane, Wenjin Hu, Patty Jablonski, Hai Lin, Christopher Lynch, and Ralph Eric McGregor. *Encoding First Order Proofs in SAT*, CADE-21, 2007.
- Jeremy Bongio, Cyrus Katrak, Hai Lin, Christopher Lynch, and Ralph Eric McGregor. *Encoding First Order Proofs in SMT*. ENTCS, 198(2):71–84, 2008.

◆□ ▶ ◆□ ▶ ◆ ■ ▶ ◆ ■ ● ⑦ Q ◎ 11/26

## Proof encoding and constraints

- We generate constraints that a sequence of natural numbers represents a valid proof.
- Proofs by cases are encoded by associating nesting information to each proof step.
- Each proof consists of steps of the following types: Assumption, MP, FirstCase, SecondCase, QEDbyCases, QEDbyAssumption, QEDbyEFQ
- Contents corresponds to a disjunction in a proof step, Goal is *true* iff Contents is the goal...
- There are also global constraints

◆□▶ ◆舂▶ ◆臣▶ ◆臣▶ 臣 - のへで 12/26

## Example: Constraints for steps QEDbyEFQ

- Each proof step has one of the above sorts and meets some constraints
- For instance, if the step *s* is of the kind QEDbyEFQ, then the following conditions hold:

• StepKind(
$$s$$
) = QEDbyEFQ

```
2 s > 0
```

- 3 contents $(s-1)(0) = \bot$
- step s is the goal

Solution Nesting 
$$(s) = Nesting (s - 1)$$

◆□▶ ◆舂▶ ◆臣▶ ◆臣▶ 臣 - 釣�♡ 13/26

## Pipeline

- A maximal proof length M is given.
- Proof steps and the constraints are encoded by natural numbers.
- A constraint solver (for linear arithmetic, for instance), is invoked to find a model.
- There is a proof of length ≤ M iff there is a model for the constraints.
- If there is a model, then a proof can be reconstructed from it.
- A proof for a proof assistant, a readable proof, an illustrated proof then can be constructed from the proof.

◆□▶ ◆舂▶ ◆≧▶ ◆≧▶ ≧ のへで 14/26

Given a theory  $\mathcal{T}$  and a conjecture G, assuming that  $\mathcal{T} \not\models G$ and  $\mathcal{T} \not\models \neg G$ , the objective is to find a set of atomic formulae F, such that it holds:

- $\mathcal{T}, F \vdash G$
- the set  $\{\mathcal{T}, F\}$  is consistent

The formulas in F are called the abducts.

There can be additional conditions. In Larus (an abduct makes the step i):

- StepKind(i) = Assumption
- Output: Nesting(i) = 1
- Cases(i) = false
- OntentsPredicate(i, 0) < sizeof (Signature)</p>
- for each argument j (up to maximal arity): ContentsArgument(i, 0, j) < sizeof (Constants)</p>
- Goal(i) = false
- **Output Output Output

  <b>Output Output

  <b>Output Output

  <b>Output Output

  <b>Output Output

  <b>Output Output

  <b>Output

  <**

# Completing incomplete premises: Abduction (3/5)



The conjecture cannot be proved, but Larus offers two abducts:

```
1. set:

1. ((q(b)))

Abducts CONSISTENT!

Conjecture: \forall X (q(X) \Rightarrow s(X))

2. set:

1. ((p(b)))

Abducts CONSISTENT!

Conjecture: \forall X (p(X) \Rightarrow s(X))
```

# Completing incomplete premises: Abduction (4/5)



Let ABCD be a quadrilateral. Let E, F, G the midpoints of AB, BC et CD respectively. Let H be a point. Under which assumption the quadrilateral EFGH is a parallelogram ?

 $\longrightarrow$  H should be the midpoint of segment *AD*.

・ロト ・ 同ト ・ ヨト ・ ヨト

# Completing incomplete premises: Abduction (5/5)

Consider arbitrary a, b, c, d, e, f, g, h such that:

- $\neg col(b, d, a)$ ,
- $\neg col(b, d, c)$ ,
- $\neg col(a, c, b)$ ,
- $\neg col(a, c, d)$ ,
- $\neg col(e, f, g)$ ,

- $b \neq d$ .
- $a \neq c$ ,
- midpoint(a, e, b),
- midpoint(b, f, c),
- midpoint(c, g, d).

◆□▶ ◆母▶ ◆ 臣▶ ◆ 臣▶ 臣 の Q @ 19/26

It should be proved that pG(e, f, g, h). Abducts found: midpoint(d, h, a) 1. par(a, c, e, f) (by MP, from  $\neg col(a, c, b)$ , midpoint(b, f, c), midpoint(a, e, b)

using axiom triangle\_mid\_par\_strict; instantiation:  $A \mapsto a, B \mapsto c, C \mapsto b, P \mapsto f, Q$  $\mapsto e$ )

## Completing incomplete goals: Deducts (1/2)



Let ABCD be a quadrilateral. Let E, F, G, H be the midpoints of the segments [AB], [BC], [CD] and [DA] respectively. What can we say about EFGH ?

・ロト ・ 同ト ・ ヨト ・ ヨト

 $\longrightarrow$  EFGH is a parallelogram.

## Completing incomplete goals: Deducts (2/2)

#### It should be proved that $_{-}(e, f, g, h)$ .

- 2. par(a, c, e, f) (by MP, from  $\neg col(a, c, b)$ , midpoint(b, f, c), midpoint(a, e, b)using axiom triangle\_mid\_par\_strict; instantiation:  $A \mapsto a, B \mapsto c, C \mapsto b, P \mapsto f, Q$  $\mapsto e$ )
- 3. par(a, c, h, g) (by MP, from  $\neg col(a, c, d)$ , midpoint(c, g, d), midpoint(a, h, d)using axiom triangle\_mid\_par\_strict; instantiation:  $A \mapsto a, B \mapsto c, C \mapsto d, P \mapsto g, Q$  $\mapsto h$ )
- 4. par(e, f, g, h) (by MP, from par(a, c, e, f), par(a, c, h, g),  $\neg col(e, f, g)$  using axiom lemma\_par\_trans; instantiation:  $A \mapsto e, B \mapsto f, C \mapsto a, D \mapsto c, E \mapsto g, F \mapsto h$ )
- 5. Proved by assumption! (by QEDas)

◆□ ▶ ◆母 ▶ ◆ 臣 ▶ ◆ 臣 ▶ ○ 臣 ⑦ Q @ 21/26

#### Completing incomplete proofs: Hints (1/3)



< □ ▶ < @ ▶ < E ▶ < E ▶ ○ Q ○ 22/26

# Completing incomplete proofs: Hints (2/3)

- Hint can be found in an informal proof (for instance, in a textbook), from machine verifiable proof, or from memory!
- For a proof or a proof step, hint can specify:
  - the predicate symbol
  - arguments in the atomic formula
  - the ordinal of a proof step
  - the axiom applied in the step
  - ...
- In other provers, such hints are extremely difficult to use
- In some cases, hints can lead to significant speed-ups

◆□▶ ◆舂▶ ◆≧▶ ◆≧▶ ≧ のへで 23/26

- Using this approach, the user can add constraints either to help the prover or to find a specific proof.
- Examples:
  - predicate r must appear somewhere in the proof:
     fof(hintname0, hint, r(?,?), \_, \_)
  - ax2 must be used in the proof at step 3, instantiating both arguments with the same value

fof(hintname0, hint, \_, 3, ax2(A,A))

- Many generated abducts/deducts are ,,uninteresting" or mutually similar
- There are different restrictions in abduction considered in the literature and we will consider different criteria for filtering out ,,interesting "abducts/deducts (for instance, minimal in some sense)

◆□▶ ◆母▶ ◆ 国▶ ◆ 国▶ ○ 国 · · · ○ ○ 25/26

- We have shown that we can extend a prover, which uses constraint solving, so that it can complete:
  - partially specified hypotheses
  - partially specified conclusions
  - partially specified proofs
- All three tasks fit naturally into *proving as constraint solving* paradigm: it is only that some constraints are added or deleted
- To our knowledge, this approach is new, and we are not aware of any other systems that tackle these three completion problems.

◆□▶ ◆母▶ ◆ 臣▶ ◆ 臣▶ 臣 の Q @ 26/26